



International Journal on Recent Researches In Science, Engineering & Technology

A Journal Established in early 2000 as National journal and upgraded to International journal in 2013 and is in existence for the last 10 years. It is run by Retired Professors from NIT, Trichy.

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ISSN (Print) : 2347-6729

ISSN (Online) : 2348-3105

Volume 2, Issue 10,

October 2014

DIIF IF :1.46

SJIF IF: 1.329

Pick and Place System With Camera Vision System Used In Industries

A. Aravindh Kumar and V. Dinesh

Abstract - The main aim of the present work is to pick the rejected or reworked parts by the visual sensors from the conveyor and to keep them in a bin. It works according to the status of camera vision system. If it is implemented human errors will be reduced. They will not mix with correct parts. Schematic diagram of pick and place camera vision system